### **RAMCloud Design Review**

# Recovery

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### Implications of Single Copy in Memory

- Problem: Unavailability
  - If master crashes unavailable until read from disks on backups
  - Read 64 GB from one disk? 10 minutes
- Leverage scale to get low-latency recovery
  - Lots of disk heads, NICs, CPUs
  - Our goal: recover in 1-2 seconds
    - Is this good enough?

# **Overview**

### Master Recovery

- o 2-Phase
- Sharding

#### Failures

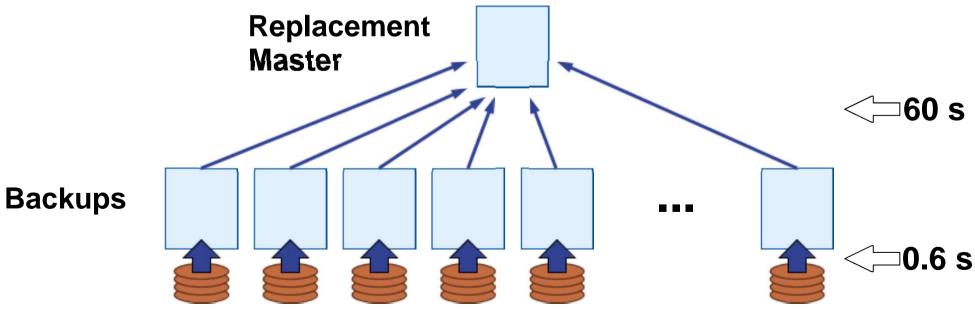
- Backups
- Rack/Switch
- Datacenter
- Power

### **Fast Recovery**

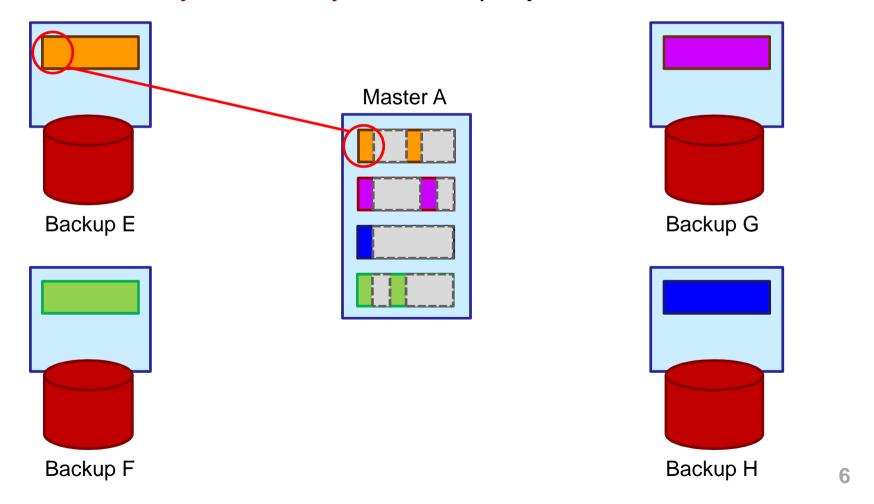
- Idea: Leverage many spindles to recover quickly
  - Log segments broadly scattered throughout backups
    - Not just great write throughput
    - Take advantage of read throughput
- Reincarnate masters exactly
  - Tables
  - Indexes
  - Preserves locality

### Fast Recovery: The Problem

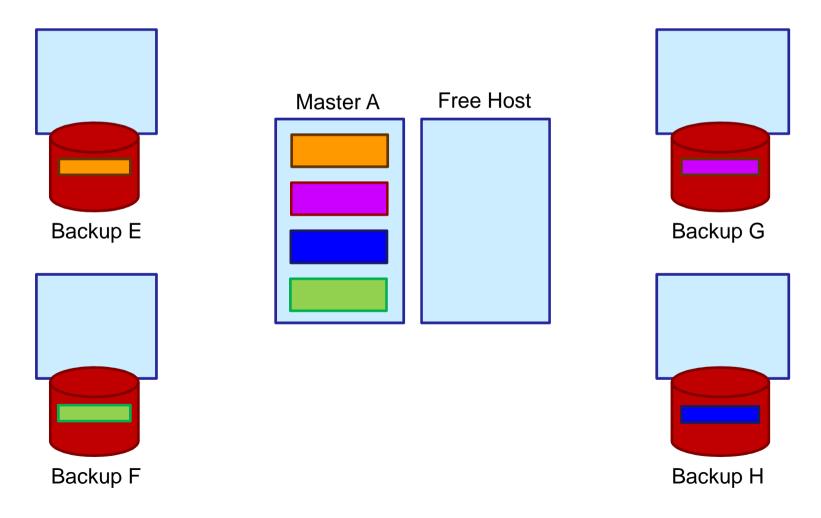
- After crash, all backups read disks in parallel
  (64 GB/1000 backups @ 100 MB/sec = 0.6 sec, great!)
- Collect all backup data on replacement master (64 GB/10Gbit/sec ~ 60 sec: too slow!)
   Network is the bottleneck!



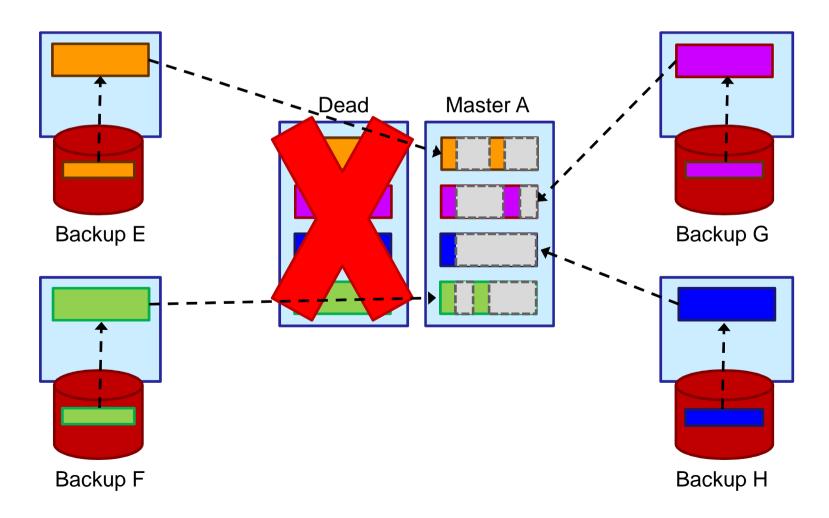
- Idea: Is all the data really needed to function?
  - o No
  - Just the hashtable
  - Data already in memory on backups, just need to know where



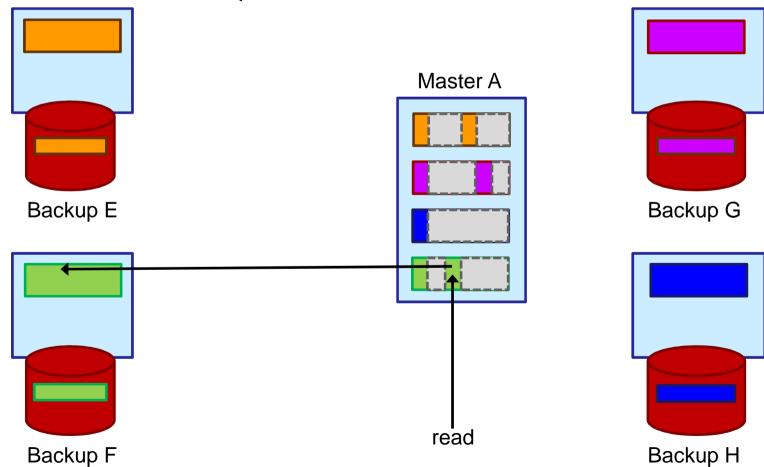
- Phase #1: Recover Metadata (< 1s)</li>
  - Read all segments into memories of backups
  - Send only location info to replacement master
  - Elapsed time depends on # objects



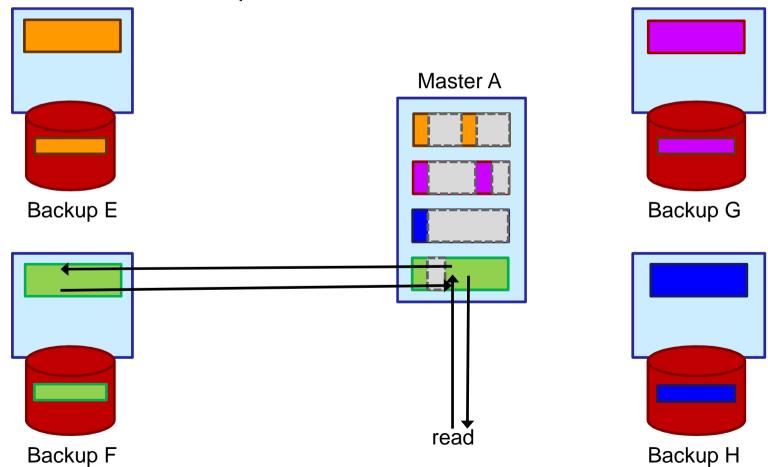
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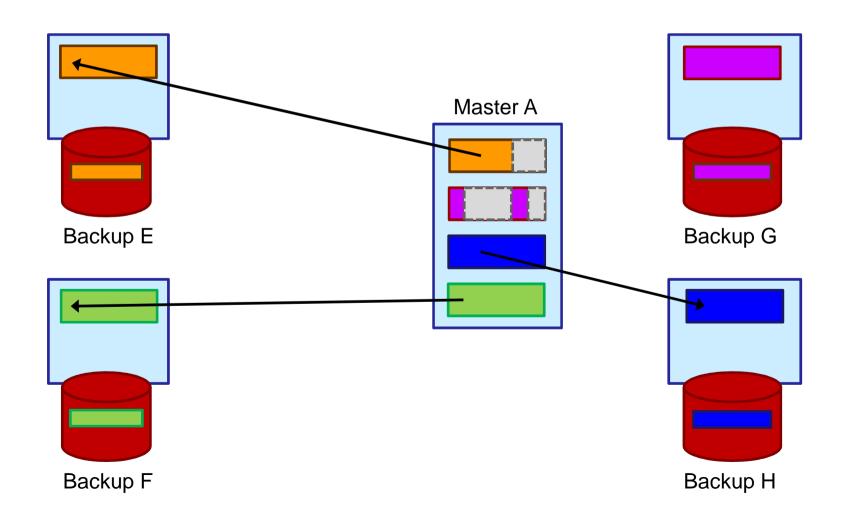
- Phase #2: Proxy & Recover Full Data (~60s)
  - System resumes operation:
    - Fetch on demand from backups
    - 1 extra round trip on first read of an object
    - Writes are full speed



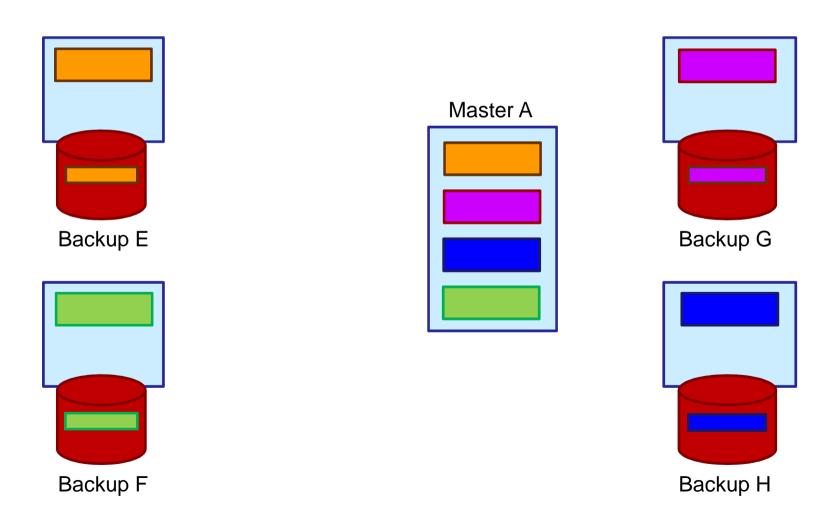
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- Phase #2: Proxy & Recover Full Data (~60s)
  - Transfer data from backups in between servicing requests



Performance normal after Phase #2 completes



# 2-Phase Recovery: Thoughts

### Recovers locality by recovering machines

#### Need to talk to all hosts

- Because backup data for a single master is on all machines
- o How bad is this?
- Alternatives?

### Doesn't deal with heterogeneity

- Machine is the unit of recovery
- Can only recover a machine to one with more capacity

### Doesn't solve index recovery

- Large indexes need large amount of data to recover
- 64 GB master containing a 64 GB index

#### Bi-modal Utilization

Must retain pool of empty hosts

### 2-Phase Recovery: Problem

#### Hashtable inserts become the new bottleneck

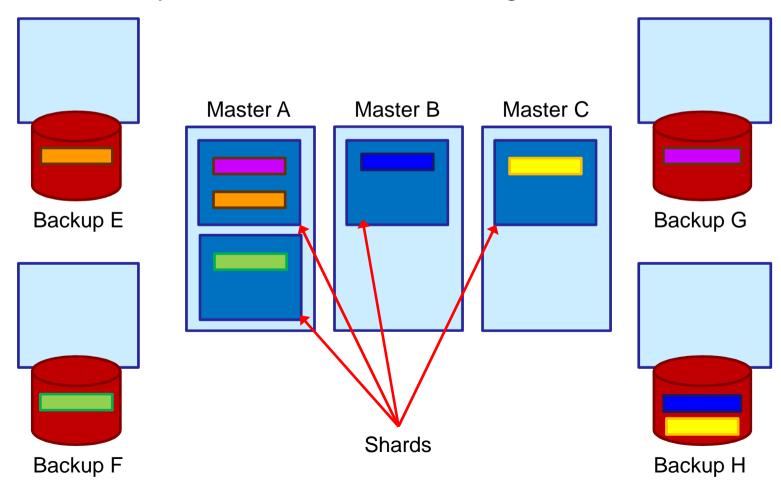
- Master can have 64 million 1 KB objects
- Hashtable can sustain about 10 million inserts/s
- 6.4 s is over our budget
- Can use additional cores, but objects could be even smaller

### Unsure of a way to recover the master in time

- Constrained by both CPU and NIC
- Recovery to single master is a bottleneck

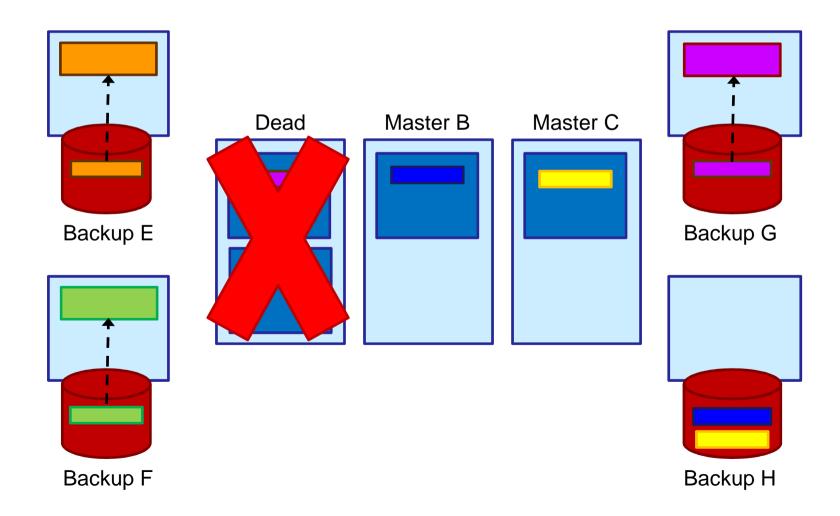
# **Sharded Recovery**

- Idea: Leverage many hosts to overcome bottleneck
  - Problem is machines are large so divide them into shards
  - Recover each shard to a different master
  - Just like a machine
    - Contains any number of tables, table fragments, indexes, etc.



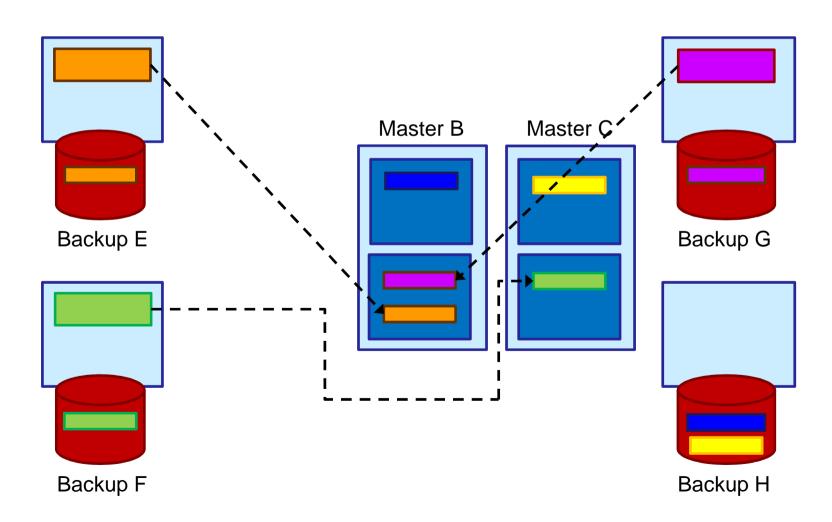
# **Sharded Recovery**

Load data from disks



# **Sharded Recovery**

- Reconstitute shards on many hosts
- 64 GB / 100 Shards = 640 MB
- 640 MB / 10 GBit/s = 0.6 s for full recovery



# **Sharded Recovery: Thoughts**

- ✓ It works: meets availability goals
  - Can tune time by adjusting shard size
- Helps with heterogeneity
  - Unit of recovery is no longer a machine
- Increases host/shard related metadata
  - Coordinator maintains mapping of object ID ranges to masters
    - Clients cache this information
  - Sharding each master 100 ways does not increase metadata 100x
  - Many tables fit within 640 MB
    - These introduce no new mappings
  - Only 100x increase if all tables are on all shards
  - Shards are still large enough to provide locality
- Need to talk to all hosts

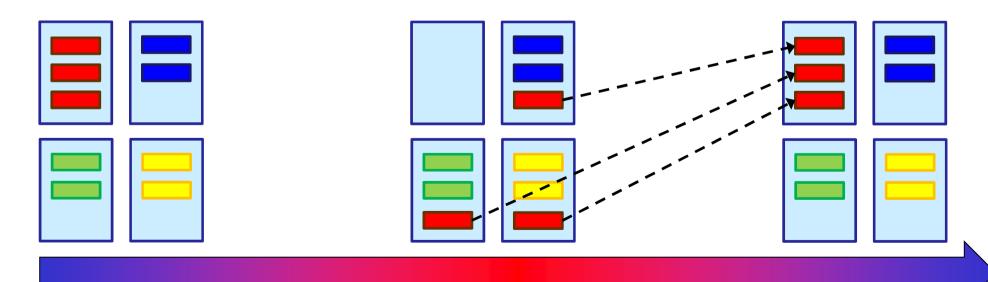
# **Sharded Recovery: Thoughts**

#### Recover to least utilized hosts

- Using all the machines all the time
- Based on RAM, NIC, CPU, or something sophisticated
- Evens out host utilization (unlike 2-Phase approach)

### Does not recover locality

- But, no worse than 2-Phase
- Shared approach can recover as fast as Phase #1
- And can restore locality as fast as Phase #2



Phase #1 **0.6s** Phase #2 **10s** 

### **Master Recovery: Summary**

- Use scale in two ways to achieve availability
  - Scatter reads during recovery to overcome disk bottleneck
  - Scatter rebuilding to overcome CPU and network bottlenecks
  - Effectively we have scale driving lower-latency
- Remaining Issue: How do we get information we need for recovery?
  - Every master recovery involves all backups

# Failures: Backups

- On backup failure the coordinator broadcasts
- All masters check their live segments
- If any were backed up on that host
- Rewrite those segments (from RAM) elsewhere

### Failures: Racks/Switches

- Rack failures handled the same as machine failures
  - Consider all the machines in the rack dead
- Careful selection of segment backup locations
  - Write backups for segments to other racks
    - As each other
    - As the master
  - Changes as masters recover
    - Can move between racks
  - Masters fix this on recovery
    - Rewrite segments elsewhere, if needed
- Question: Minimum RAMCloud that can sustain an entire rack failure and meet recovery goal?
  - 100 shards to recover a single machine in 0.6s
  - 50 dead \* 50 shards, need 2500 machines to make 1.2s
  - Don't pack storage servers in racks, mix with app servers

### **Failures: Power**

- Problem: Segments are buffered temporarily in RAM
  - Even after the put has returned as successful to the application
- Solution: All hosts have on-board battery backup
- Flush all "open" segments on fluctuation
  - Any battery should be easily sufficient for this
  - About r open segments per shard per backup
    - r = 3 with 100 shards/master
    - Must flush 300 \* 8MB = 24s
- No battery?
  - Deal with lower consistency
  - Synchronous writes
- Question: Is there some cost effective way to get 10-20s of power?

### **Failures: Datacenter**

- Durability guaranteed by disks, no availability
  - Modulo nuclear attacks
- No cross-DC replication in version 1
  - Latency can't be reconciled with consistency
  - Aggregate write bandwidth of 1000 host RAMCloud
    - 100 MB/s \* 1000 = 1 Tbit/s
- Application level will do much better
  - Application can batch writes
  - Application understands consistency needs
- Is this something we need to support?

# **Summary**

- Distribute Backup Data
  - Scatter reads during recovery to overcome disk bottleneck
- Sharded Recovery
  - Scatter rebuilding to overcome CPU and network bottlenecks
- Use scale in two ways to achieve availability
- Scale driving lower-latency

# **Discussion**