RAMCloud Design Review

Recovery

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Implications of Single Copy in Memory

- Problem: Unavailability
 - If master crashes unavailable until read from disks on backups
 - Read 64 GB from one disk? 10 minutes
- Leverage scale to get low-latency recovery
 - Lots of disk heads, NICs, CPUs
 - Our goal: recover in 1-2 seconds
 - Is this good enough?

Overview

Master Recovery

- o 2-Phase
- Sharding

Failures

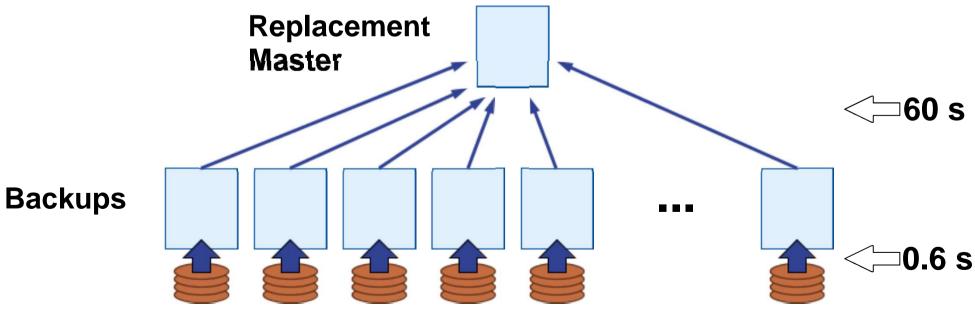
- Backups
- Rack/Switch
- Datacenter
- Power

Fast Recovery

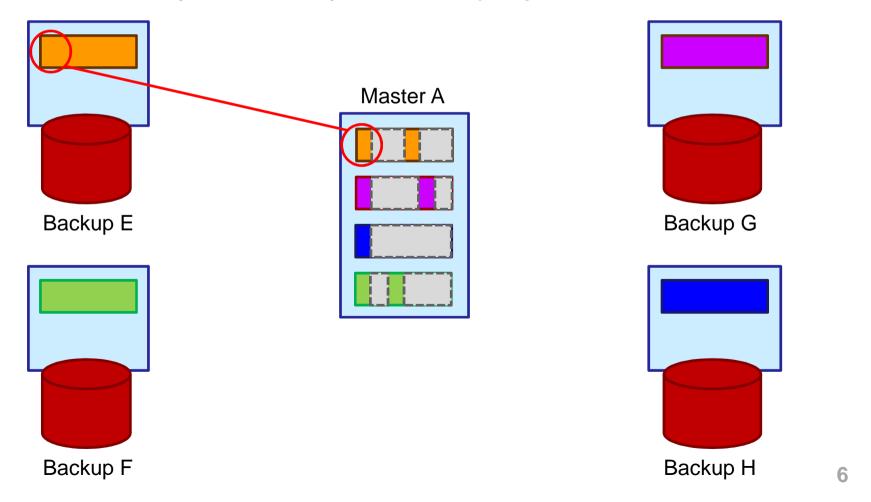
- Idea: Leverage many spindles to recover quickly
 - Log segments broadly scattered throughout backups
 - Not just great write throughput
 - Take advantage of read throughput
- Reincarnate masters exactly
 - Tables
 - Indexes
 - Preserves locality

Fast Recovery: The Problem

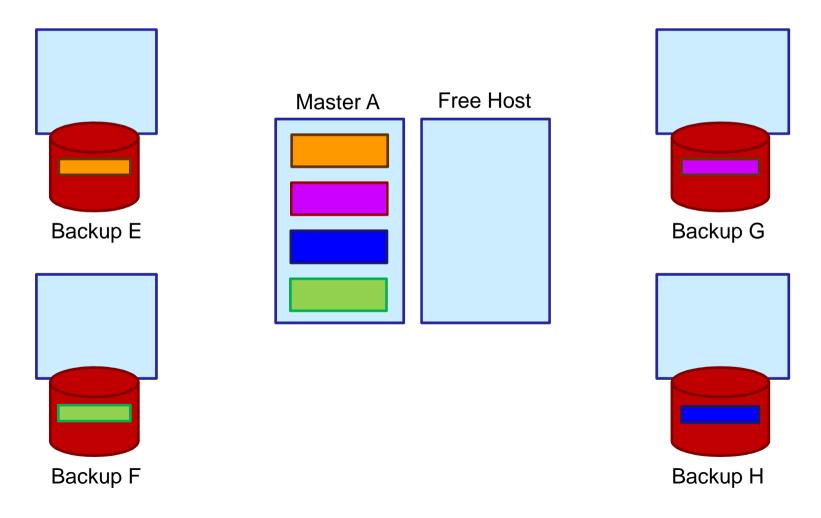
- After crash, all backups read disks in parallel
 (64 GB/1000 backups @ 100 MB/sec = 0.6 sec, great!)
- Collect all backup data on replacement master (64 GB/10Gbit/sec ~ 60 sec: too slow!)
 Network is the bottleneck!



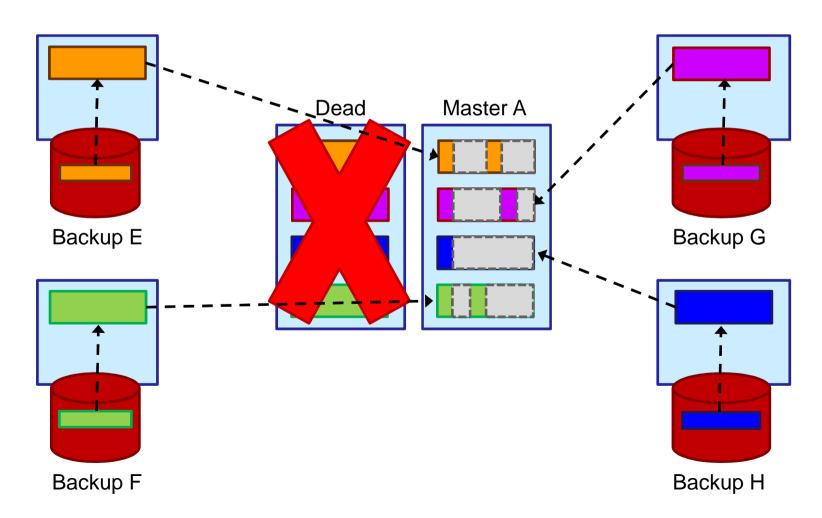
- Idea: Is all the data really needed to function?
 - o No
 - Just the hashtable
 - Data already in memory on backups, just need to know where



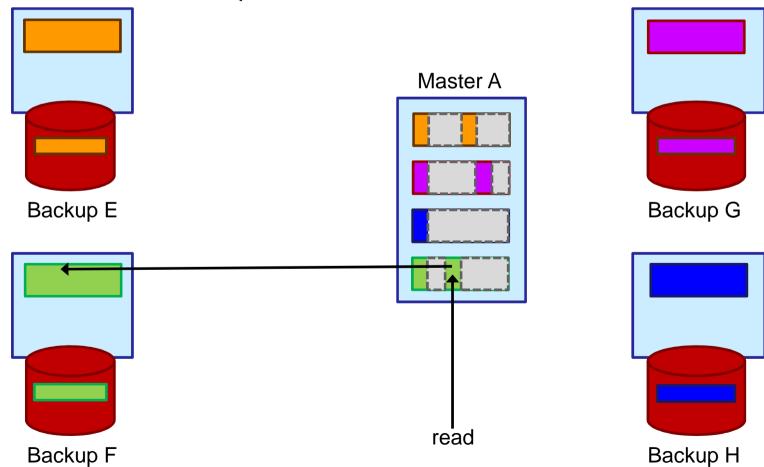
- Phase #1: Recover Metadata (< 1s)
 - Read all segments into memories of backups
 - Send only location info to replacement master
 - Elapsed time depends on # objects



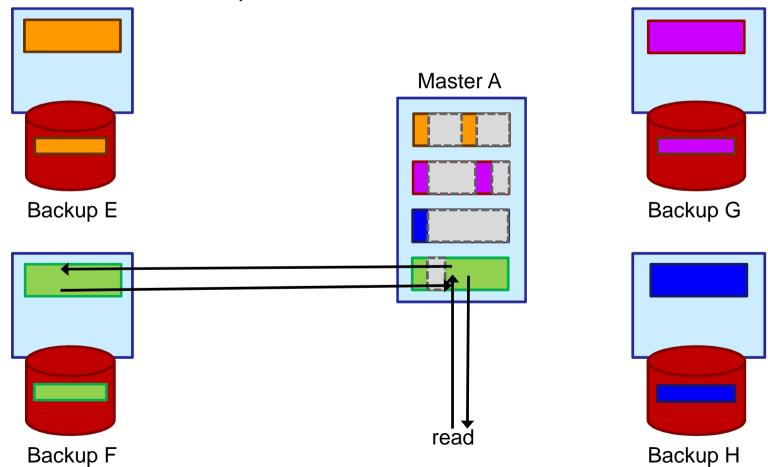
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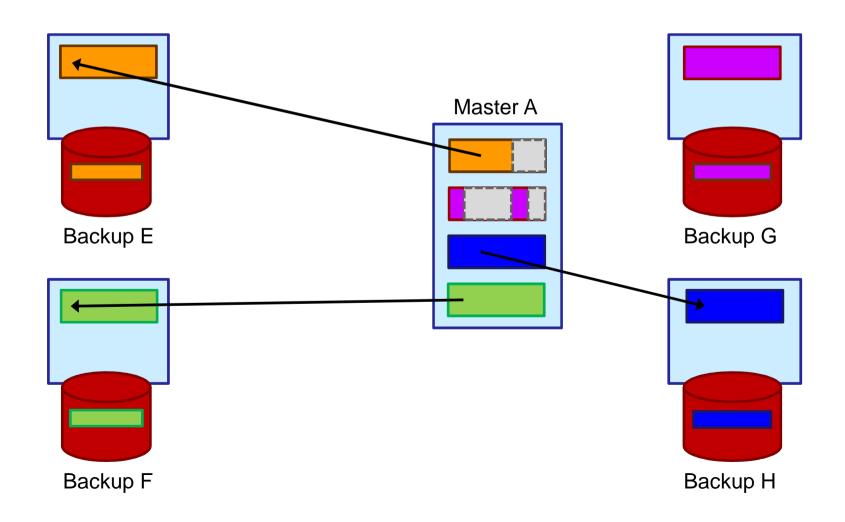
- Phase #2: Proxy & Recover Full Data (~60s)
 - System resumes operation:
 - Fetch on demand from backups
 - 1 extra round trip on first read of an object
 - Writes are full speed



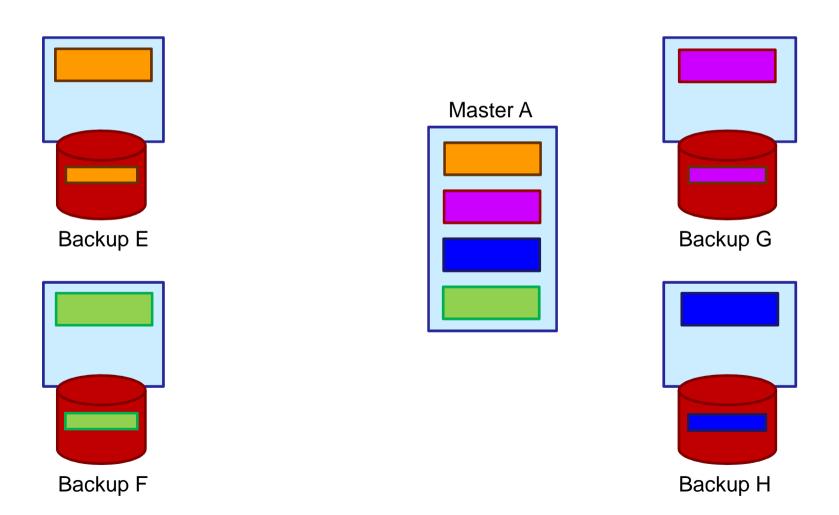
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- Phase #2: Proxy & Recover Full Data (~60s)
 - Transfer data from backups in between servicing requests



Performance normal after Phase #2 completes



2-Phase Recovery: Thoughts

Recovers locality by recovering machines

Need to talk to all hosts

- Because backup data for a single master is on all machines
- o How bad is this?
- Alternatives?

Doesn't deal with heterogeneity

- Machine is the unit of recovery
- Can only recover a machine to one with more capacity

Doesn't solve index recovery

- Large indexes need large amount of data to recover
- 64 GB master containing a 64 GB index

Bi-modal Utilization

Must retain pool of empty hosts

2-Phase Recovery: Problem

Hashtable inserts become the new bottleneck

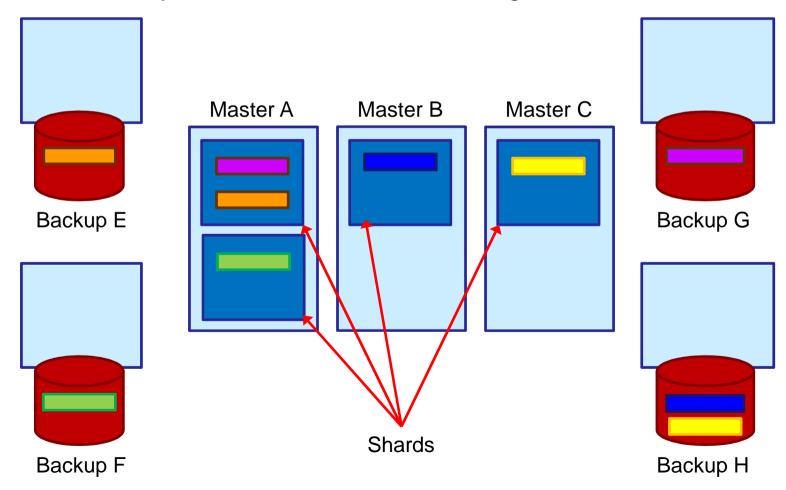
- Master can have 64 million 1 KB objects
- Hashtable can sustain about 10 million inserts/s
- 6.4 s is over our budget
- Can use additional cores, but objects could be even smaller

Unsure of a way to recover the master in time

- Constrained by both CPU and NIC
- Recovery to single master is a bottleneck

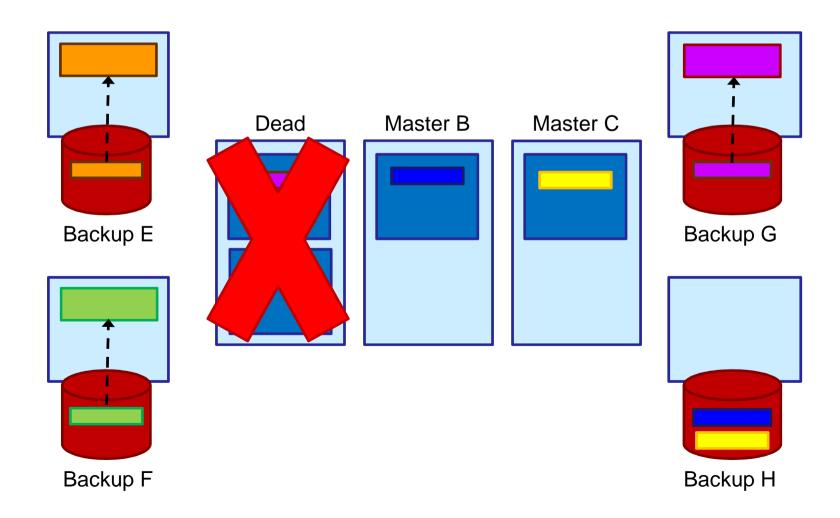
Sharded Recovery

- Idea: Leverage many hosts to overcome bottleneck
 - Problem is machines are large so divide them into shards
 - Recover each shard to a different master
 - Just like a machine
 - Contains any number of tables, table fragments, indexes, etc.



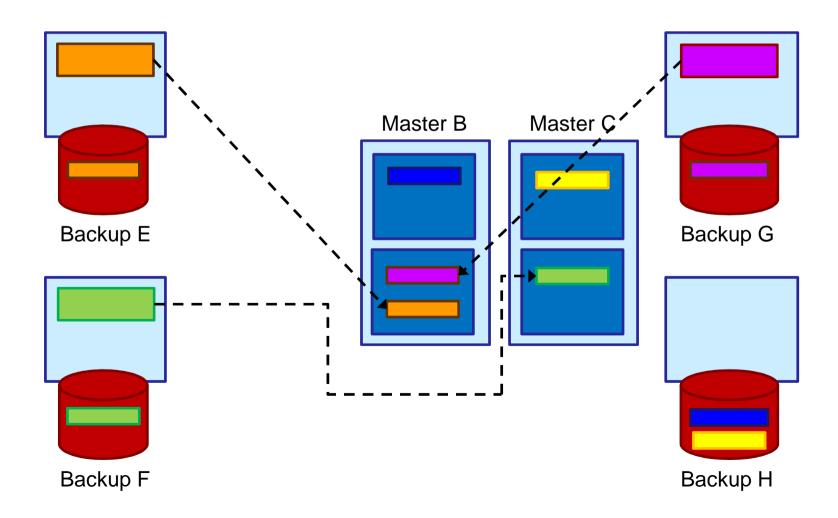
Sharded Recovery

Load data from disks



Sharded Recovery

- Reconstitute shards on many hosts
- 64 GB / 100 Shards = 640 MB
- 640 MB / 10 GBit/s = 0.6 s for full recovery



Sharded Recovery: Thoughts

- ✓ It works: meets availability goals
 - Can tune time by adjusting shard size
- Helps with heterogeneity
 - Unit of recovery is no longer a machine
- Increases host/shard related metadata
 - Coordinator maintains mapping of object ID ranges to masters
 - Clients cache this information
 - Sharding each master 100 ways does not increase metadata 100x
 - Many tables fit within 640 MB
 - These introduce no new mappings
 - Only 100x increase if all tables are on all shards
 - Shards are still large enough to provide locality
- Need to talk to all hosts

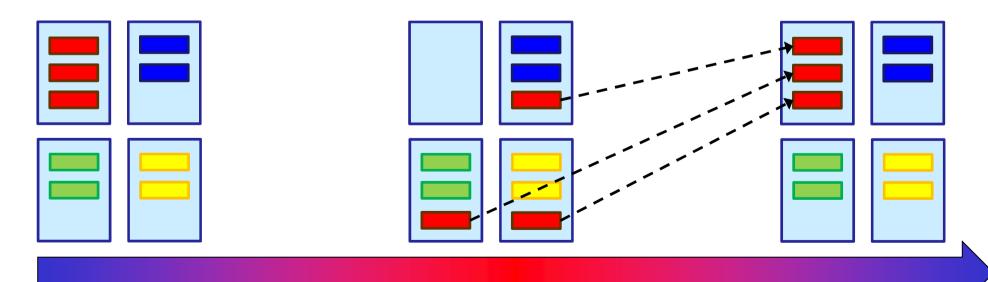
Sharded Recovery: Thoughts

Recover to least utilized hosts

- Using all the machines all the time
- Based on RAM, NIC, CPU, or something sophisticated
- Evens out host utilization (unlike 2-Phase approach)

Does not recover locality

- But, no worse than 2-Phase
- Shared approach can recover as fast as Phase #1
- And can restore locality as fast as Phase #2



Phase #1 **0.6s** Phase #2 **10s**

Master Recovery: Summary

- Use scale in two ways to achieve availability
 - Scatter reads during recovery to overcome disk bottleneck
 - Scatter rebuilding to overcome CPU and network bottlenecks
 - Effectively we have scale driving lower-latency
- Remaining Issue: How do we get information we need for recovery?
 - Every master recovery involves all backups

Failures: Backups

- On backup failure the coordinator broadcasts
- All masters check their live segments
- If any were backed up on that host
- Rewrite those segments (from RAM) elsewhere

Failures: Racks/Switches

- Rack failures handled the same as machine failures
 - Consider all the machines in the rack dead
- Careful selection of segment backup locations
 - Write backups for segments to other racks
 - As each other
 - As the master
 - Changes as masters recover
 - Can move between racks
 - Masters fix this on recovery
 - Rewrite segments elsewhere, if needed
- Question: Minimum RAMCloud that can sustain an entire rack failure and meet recovery goal?
 - 100 shards to recover a single machine in 0.6s
 - 50 dead * 50 shards, need 2500 machines to make 1.2s
 - Don't pack storage servers in racks, mix with app servers

Failures: Power

- Problem: Segments are buffered temporarily in RAM
 - Even after the put has returned as successful to the application
- Solution: All hosts have on-board battery backup
- Flush all "open" segments on fluctuation
 - Any battery should be easily sufficient for this
 - About r open segments per shard per backup
 - r = 3 with 100 shards/master
 - Must flush 300 * 8MB = 24s
- No battery?
 - Deal with lower consistency
 - Synchronous writes
- Question: Is there some cost effective way to get 10-20s of power?

Failures: Datacenter

- Durability guaranteed by disks, no availability
 - Modulo nuclear attacks
- No cross-DC replication in version 1
 - Latency can't be reconciled with consistency
 - Aggregate write bandwidth of 1000 host RAMCloud
 - 100 MB/s * 1000 = 1 Tbit/s
- Application level will do much better
 - Application can batch writes
 - Application understands consistency needs
- Is this something we need to support?

Summary

- Distribute Backup Data
 - Scatter reads during recovery to overcome disk bottleneck
- Sharded Recovery
 - Scatter rebuilding to overcome CPU and network bottlenecks
- Use scale in two ways to achieve availability
- Scale driving lower-latency

Discussion