Tablet Profiling in RAMCloud

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Recall: RAMCloud Data Model

• RAMCloud stores objects in *tables*

- Tables may span physical machines (if too large, or too hot)
- A contiguous range of a table is called a tablet

Masters are responsible for serving tablets

Example:

Table #	First Key	Last Key
12	0	2 ⁶⁴ - 1
47	63,742	5,723,742

Clients obtain a tablet map from the coordinator

Associates tablets with the master servers that own them

Even Distribution for Fast Recovery

• When failures occur, need to recover quickly (1-2 sec)



• Problem:

 Recovery time is dependent on the amount of data each recovery master recovers

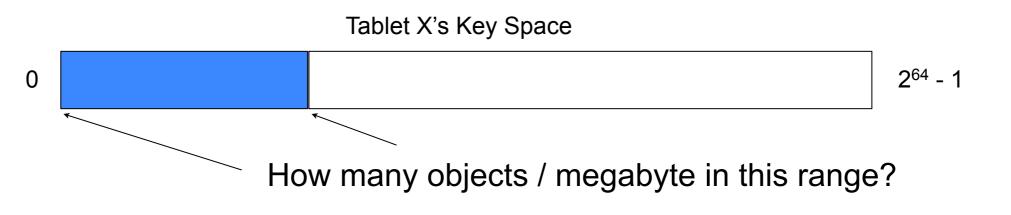
Can only recover about 600MB in 1-2 seconds

- 10GigE: ~1250MB/s max
- 600MB in, 1200MB out (R = 2, without multicast)

Per-object CPU overheads also need to be balanced

Dividing Tablets is Tricky

- How does a server evenly divide its tablets / objects?
- Can easily count how many objects and bytes are in each tablet, but what about big tablets?
 - Need to split them. But where to make the cut?
- Must ensure each division isn't too big
 - Cut the key space so each subrange contains <= 600MB of objects</p>
- Difficult because users store variable-sized objects wherever they want in the 64-bit space
 - Densities are unpredictable
 - Key density needn't imply byte density



Solution 1: Randomness

Random distribution of keys should yield a uniform density of bytes

- E.g.: Consistent hashing
- Key used by RAMCloud becomes hash(TableId, ObjectId)

Equal key subranges should have similar byte counts

TabletSize / 600MB = number of equal splits to make

Problems with this idea

- Current design allows implicit locality of data based on locality of keys (objects in same table and nearby in key space are co-located)
- Locality is useful for multi-object actions like range queries

Prefer to Keep Tablet Model

 How can we have our contiguous tablet ranges and still make recovery fast?

Need some way to efficiently partition big tablets

- And combine tablets that are small
- Let's consider a few other options...

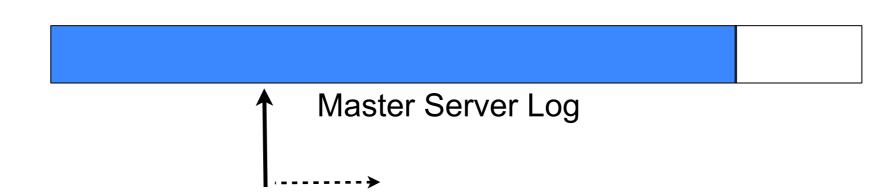
Solution 2: Batch

Compute partitions in batch

 Masters periodically scan all of their data and determine reasonable partitions for their heirs

• Multi-pass algorithm:

- Keep byte counts for N subranges
- Walk log, updating counts
- Split subranges that are too big, merge those that are too small



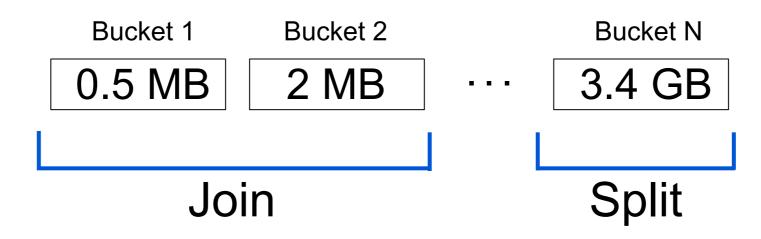
Tablet	Bucket 1	Bucket 2	Bucket 3	 Bucket N
57	374MB	0	0	 0
12	7MB	31MB	17MB	 45KB

Solution 2: Batch

 After one pass, have byte and object counts for each bucket of the key space

 Can join small buckets, but must split large ones into new buckets

- But, when we split, no idea where to draw the line. So, must break big buckets into another N
 - Another pass is needed to update counts



Solution 2: Batch

- Batch is too expensive
- Need to be able to recalculate partitions fast, since they can grow at near-network speed (~500MB/s).
 - Imbalance => longer recovery
 - Cannot afford seconds to recompute

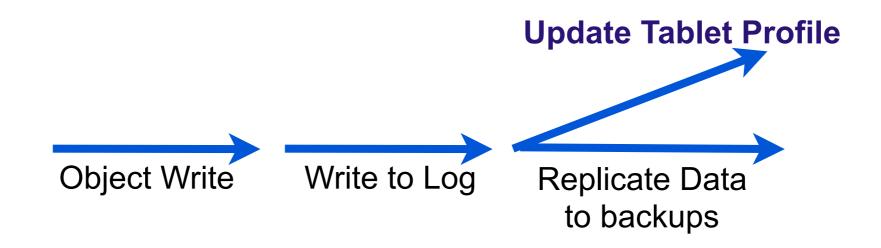
64GB's worth of objects on a single server today

- May be 100s of millions of objects
- And that's just for one pass (forget multiple passes)

Solution 3: Online

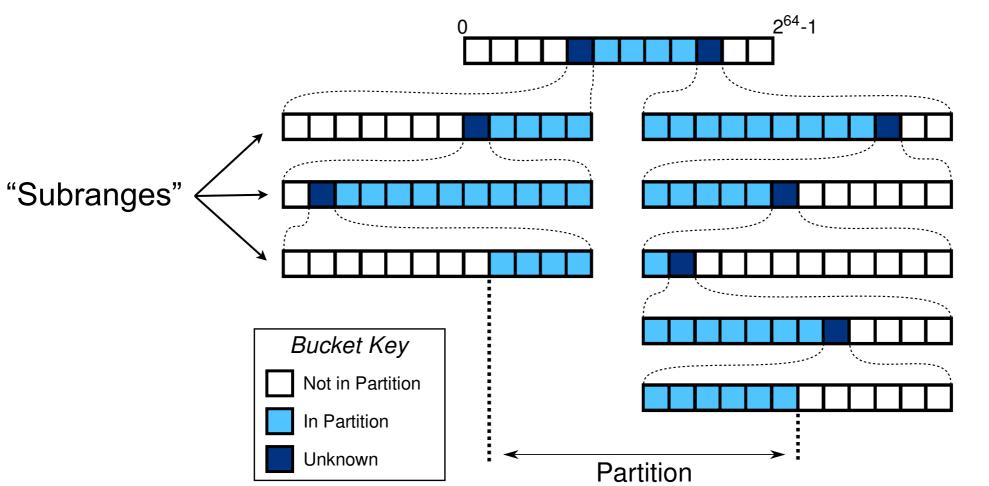
• Tablet Profiler

- Profile each tablet to track the space usage
- Do it online (i.e. during writes, while cleaning log)
- Profiler can determine data density with bounded error
- 2 operations maintain the data structure:
 - Tablet->Profiler->Track(Key, Bytes, Time) -- log writes
 - Tablet->Profiler->Untrack(Key, Bytes, Time) -- log cleaning
- Can overlap tablet profile update with data replication
 - ~5 microsecond delay to hear back from backups

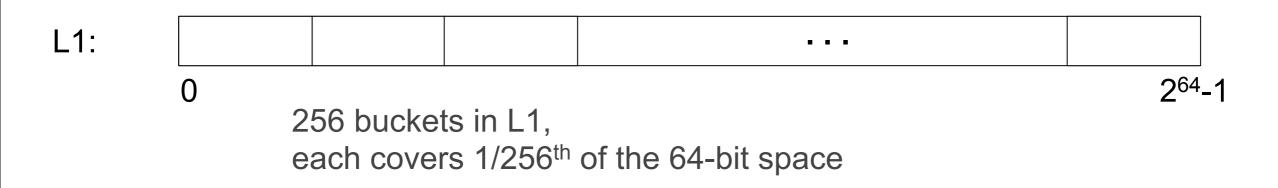


Tree structure - of key ranges and buckets

- Somewhat like a page table structure.
- Parameters:
 - *B*, the number of bits per level (Affects number of buckets)
 - S, maximum bytes in a bucket before splitting
- Each level "zooms in" on a subrange of the key space. Buckets keep byte tallies.

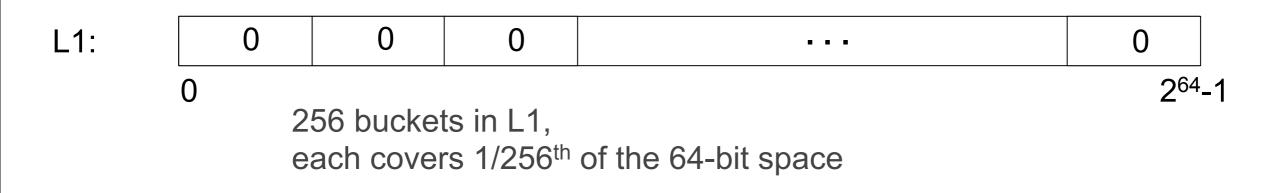


• Example: B = 8, S = 8MB



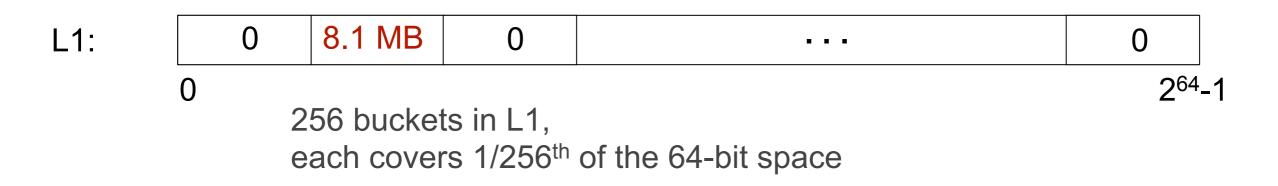
• With B = 8, there are up to 8 levels

• Example: B = 8, S = 8MB



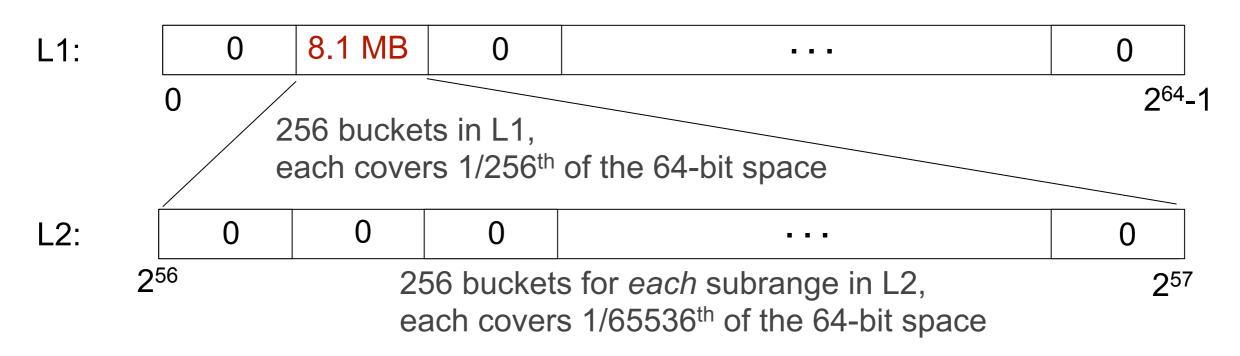
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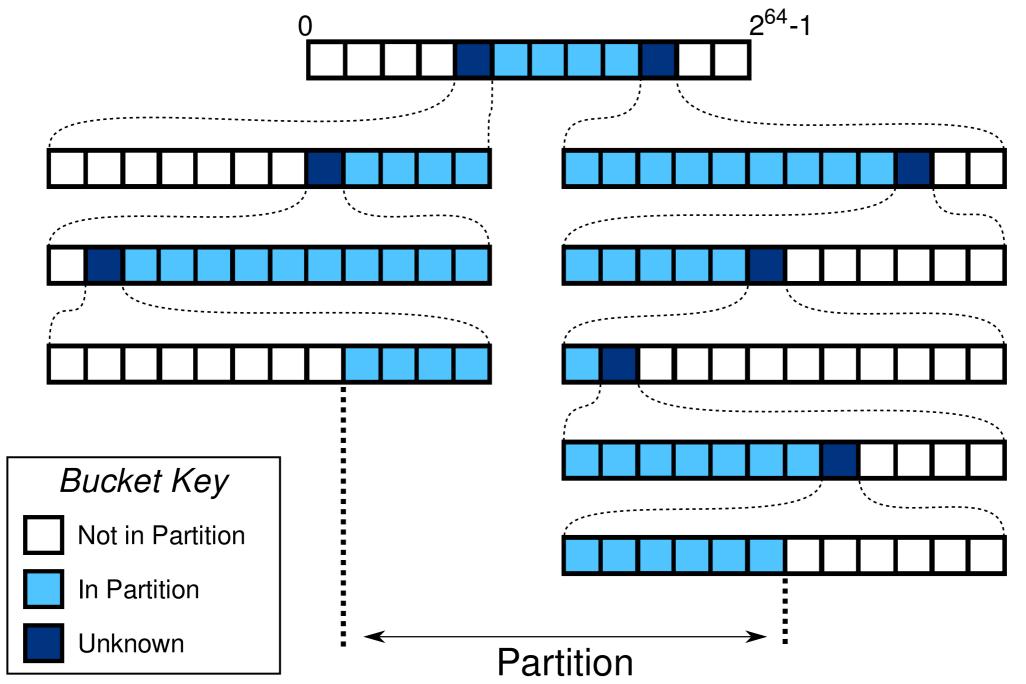


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Bounding Error

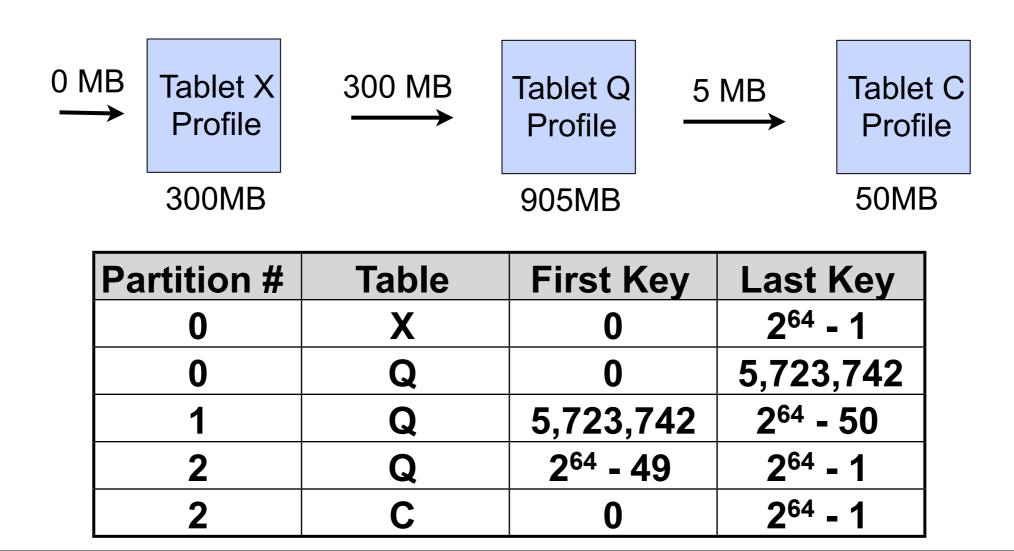
• How does this bound the error?

- Lines are drawn in leaf subranges
- We have exact counts for all data between the border subranges.



Computing Partitions

- Walk each tablet profile
- Once we reach 600MB, we've found a partition
- If we don't reach 600MB, pass the previous count into the next profile



The Last Will and Testament

• While still alive, each server maintains a *will*

Groups tablets into even, well-sized chunks (~600MB)

• The will is synchronized with the coordinator

 Needn't be strictly consistent, so long as it's complete (describes all objects owned)

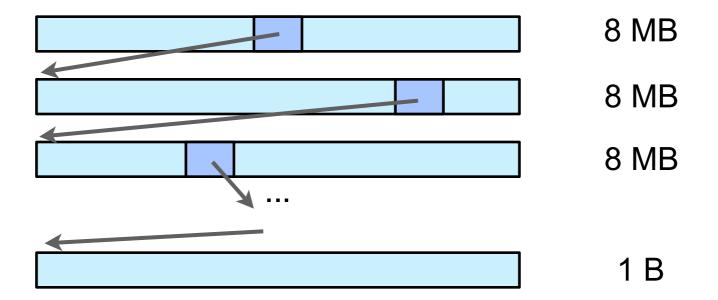
When a server crashes, the coordinator uses its will to determine what data each recovery master inherits

Recovers data according to partitions listed in the will

Partition #	Table #	First Key	Last Key
0	12	0	2 ⁶⁴ - 1
0	47	63,742	5,723,742

Space Complexity

• Worst case: Lots of small tablets that look like this:



For 8-level trees, that's 8 subrange structures for 8MB*7 + 1B ~= 56MB of data

- Each subrange (256 buckets) consumes about 16 * 256 bytes = 4K.
 - 16 bytes for object and byte counts
- 64GB / 54MB = 1200
- 1200 * 4K ~= 4.7MB, or .007% overhead.

Time Complexity

Updates require walking tree structure

- Follow logarithmic number of pointers
- < 1 microsecond</p>
- Subranges can be pooled for quick allocation if we need to expand

• B = 8: 8 levels in the tree

 Currently have plenty of time while waiting for backups to acknowledge replicated writes

Outstanding Issues

 A single object can occupy arbitrary log space and we can't split a single key...

- E.g. Update, Update, Update, ...
- Can mitigate by eliding previous objects in same segment
 - With 1MB objects and 8192 segments/server, can still have 8GB of old objects in different segments.

Wills aren't yet computed online

Batch processing too inefficient with 10,000+ tables



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