Secondary Indexing in RAMCloud

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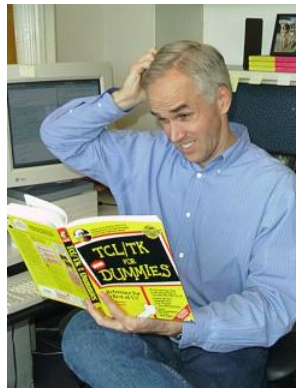
(Joint work with Arjun Gopalan, Ashish Gupta and John Ousterhout)



Introduction

- **RAMCloud 1.0**
- **Higher-level data models**
  - Without sacrificing latency and scalability
- **Secondary Indexes: lookups and range queries on attributes that are not the primary key**
- **Feedback welcome!**

Key Design Issues

- API and RAMCloud object format
- **Index placement / partitioning**
- Index memory allocation
- **Failure / Restoration**
- **Consistency**

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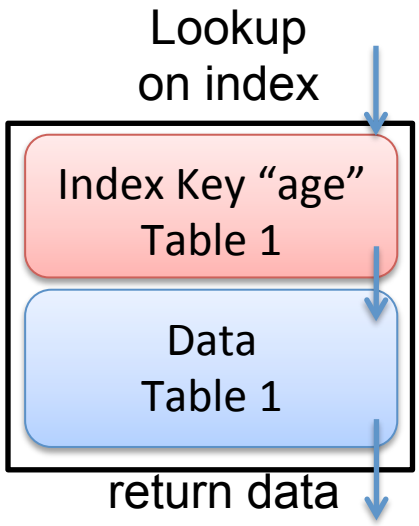
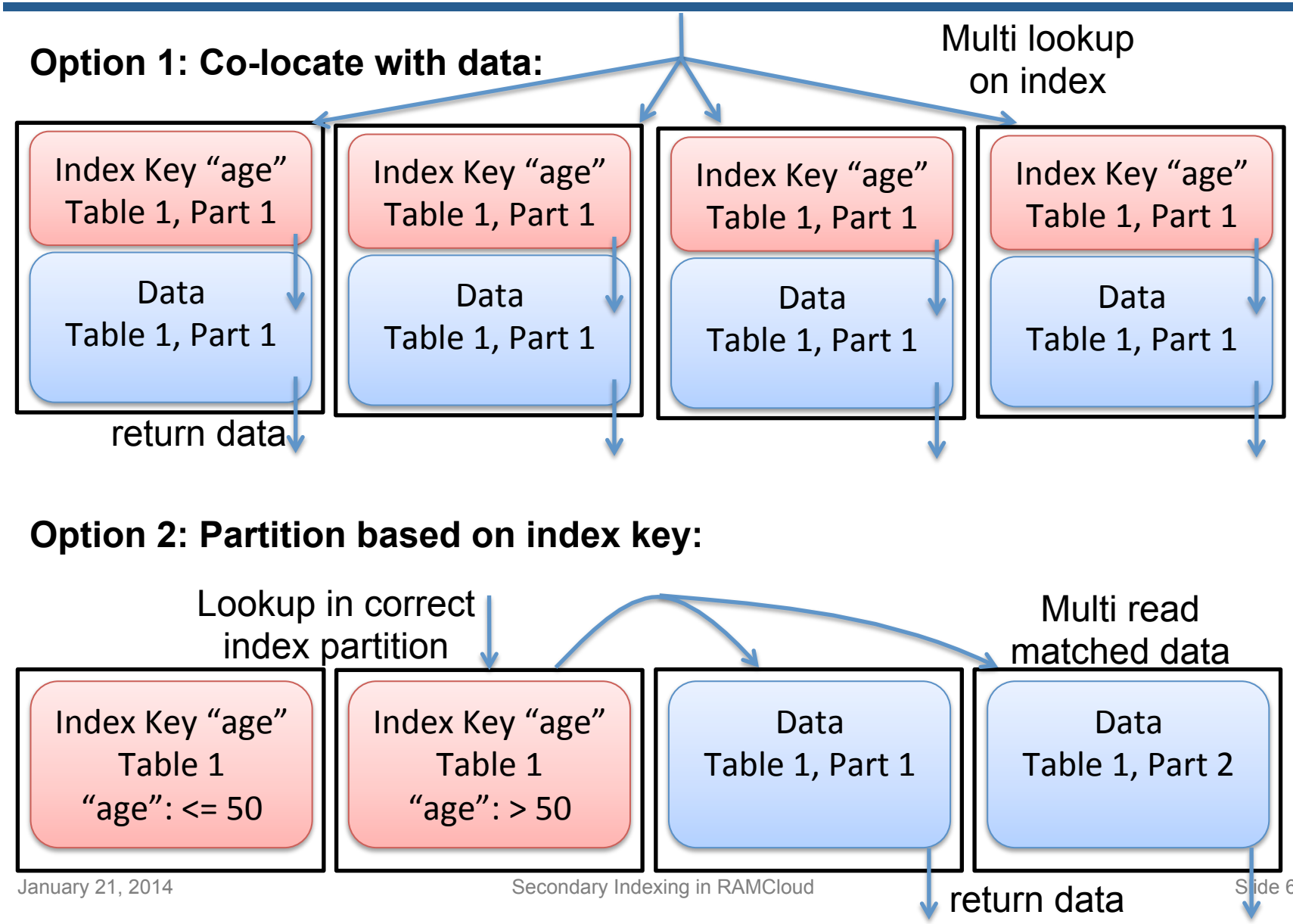
Index Placement



Index Partitioning



Index Partitioning

- **Index lookup:**
  - Assume data + index on n servers
  - Opt 1: multiLookup to n servers + local reads
  - Opt 2: lookup to index server + multiRead to x servers
    - $x \in [0, n-1]$
    - For small n: expect $x \approx n-1$
    - For large n: expect $x << n$
  - Option 2 more scalable
- **Index entry format:**
  - <index key, primary key hash>

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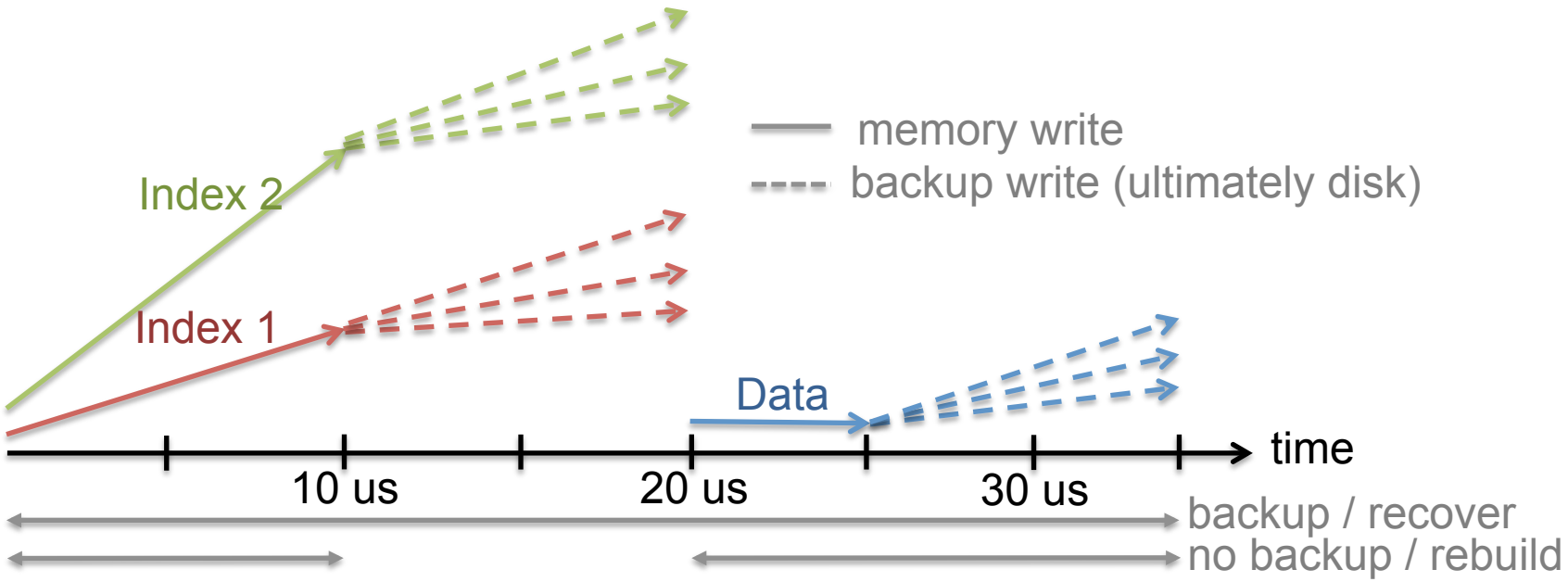
Failure / Restoration

- **Tablet Server**
  - Doesn’t affect indexes
  - “Normal” RAMCloud data recovery
- **Index server**
  - Backup / Recover
  - No backup / Rebuild

Failure/Restoration: Write Latency



	Latency	# Mem writes	# Backup writes	# Msgs from data to index servers	# Msgs to backups
No indexing	15 us	1	R	0	R
Indexing w/ backup/restore	35 us	m+1	R*(m+1)	m	R*(m+1)
Indexing w/ no-backup/rebuild	25 us	m+1	R	m	R

Failure/Restoration: Restoration Time

- **Recovery: Similar to RAMCloud data recovery: 1-2 s**
- **Rebuild: Cost analysis:**

Setting	Index partition to be recovered	1 GB
	Size of index entries	50 B (42 for key + 8 for keyhash)
	Num of index entries	2 * 10^7
Data master	Max memory bandwidth	35 GB/s
	Memory bw with overheads	20 GB/s
	Hash table size (10% of total mem)	25 GB (for 256 GB machine)
	Time to scan hash table	**1.25 s**
	Time to compare hash info from bucket	negligible
	Num objects to check if all match	2.5 * 10^9 (for 100B objects)
	Cache miss time	0.5 * 10^9 cache miss / s
	Total cache miss time	**5.12 s**
Network	Bandwidth	1 GB/s
	Time to transfer over network	**1 s**
Index Recovery Master	Time per object to insert	1.5 us
	Total time to insert	30 s
	Total time to insert with parallelization	**1 s**

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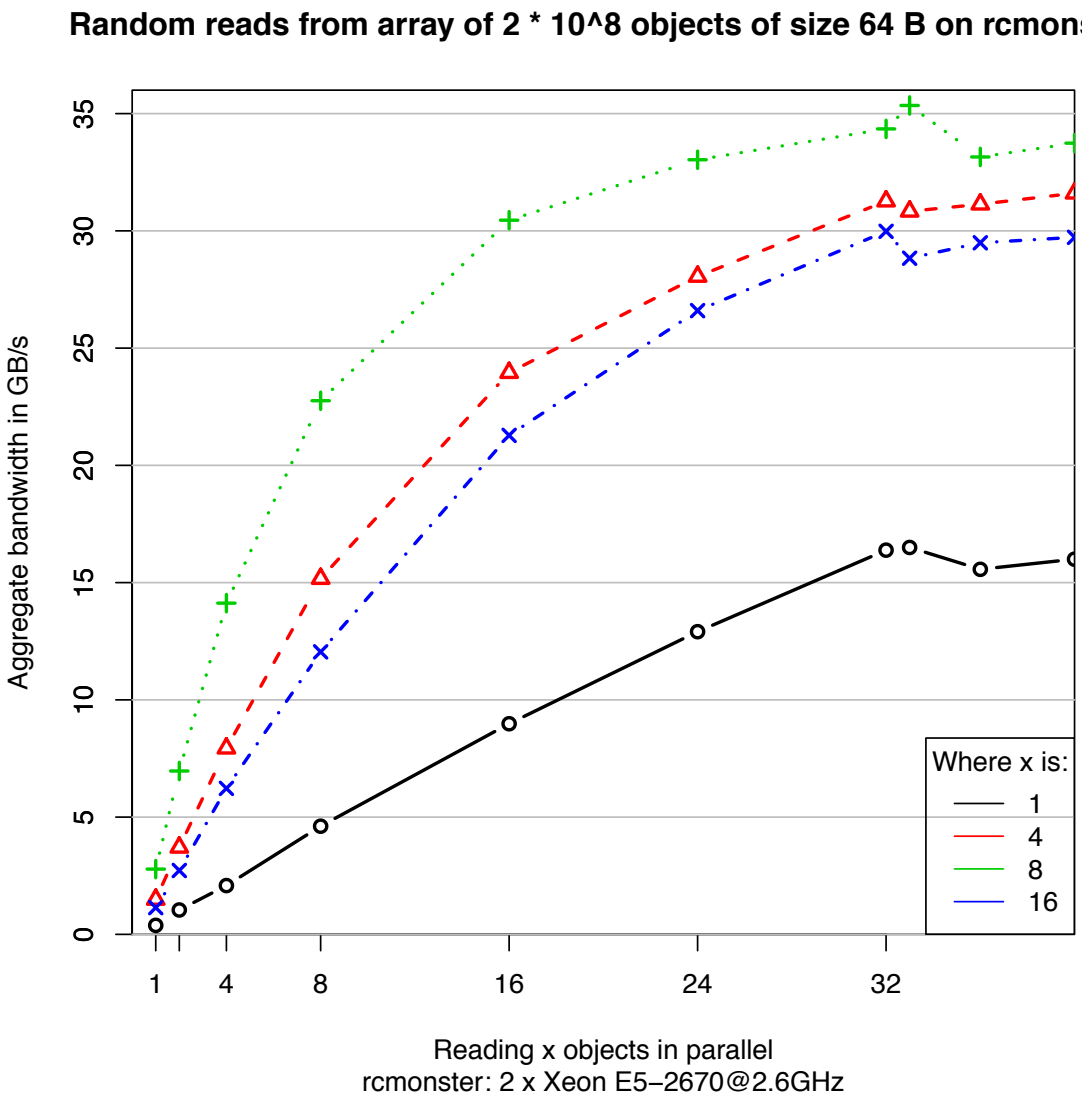
Memory Benchmark



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Consistency

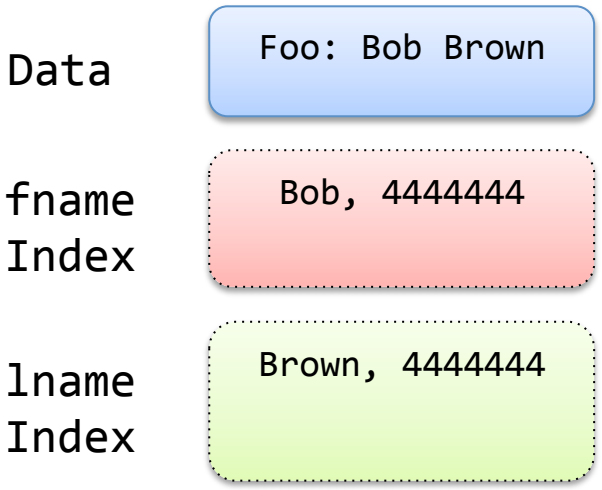
- **At any time, data is consistent with index entries corresponding to it, if:**
  - If data X exists, X is reachable from all key indexes.
  - Data returned to client is consistent with key used to look it up.
- **Provides linearizability**
  - Tradeoff with performance
- **Also desirable:**
  - Dangling pointers are not accumulating.
  - Memory footprint will not increase beyond what is necessary.

Consistency

- **Simple solution:**
  - Lock indexes and tablets for the entire duration of index update – affects scalability and performance
- **Our solution: Key Idea:**
  - Writing object is the commit point
- **Interesting situations:**
  - For multi-threaded write/read, non-locking, no failures
  - For multi-threaded write/write, non-locking, no failures
  - Failure of an Index Server
  - Failure of Master Server

Consistency

- Multi-threaded write/read, non-locking, no failures: Object Update
- There exists time x, s.t.: at time < x, client can lookup old data; at time >= x, it can lookup the new data.



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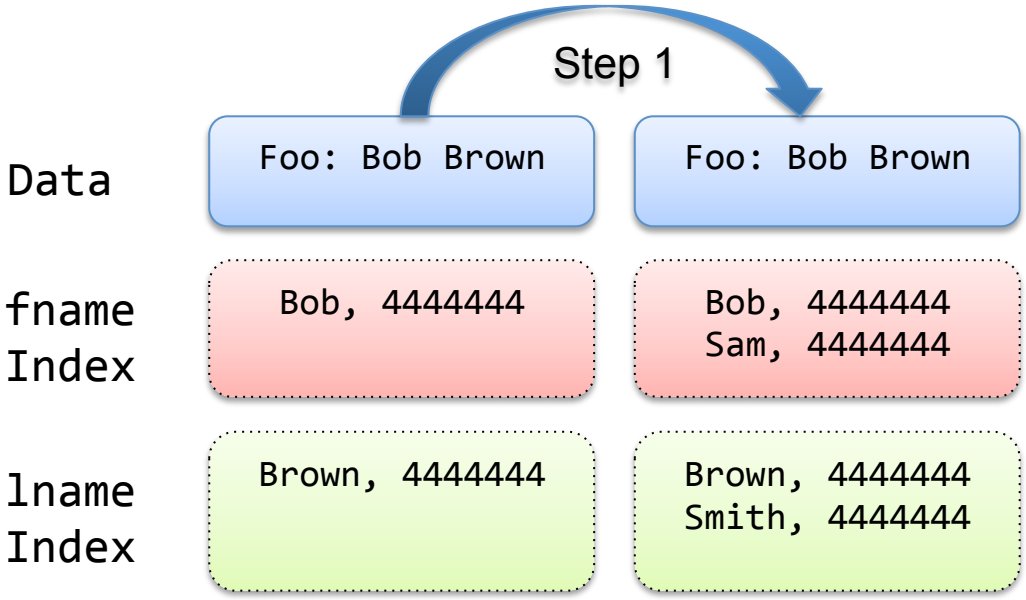

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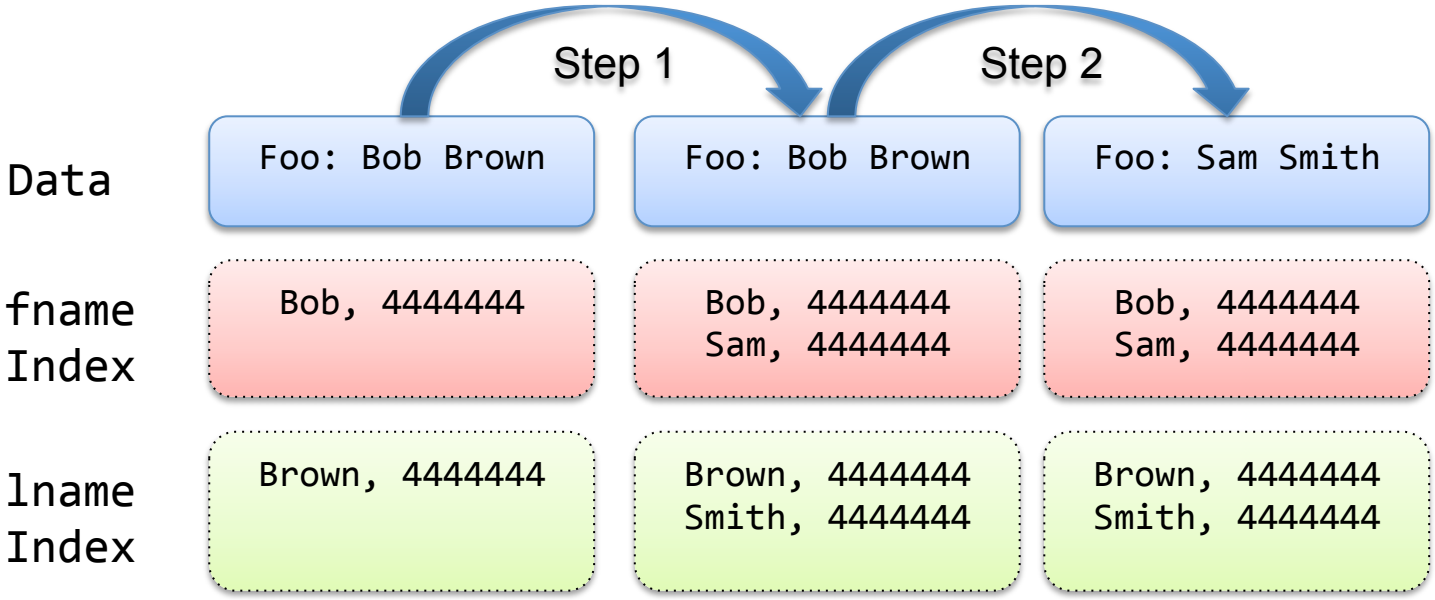

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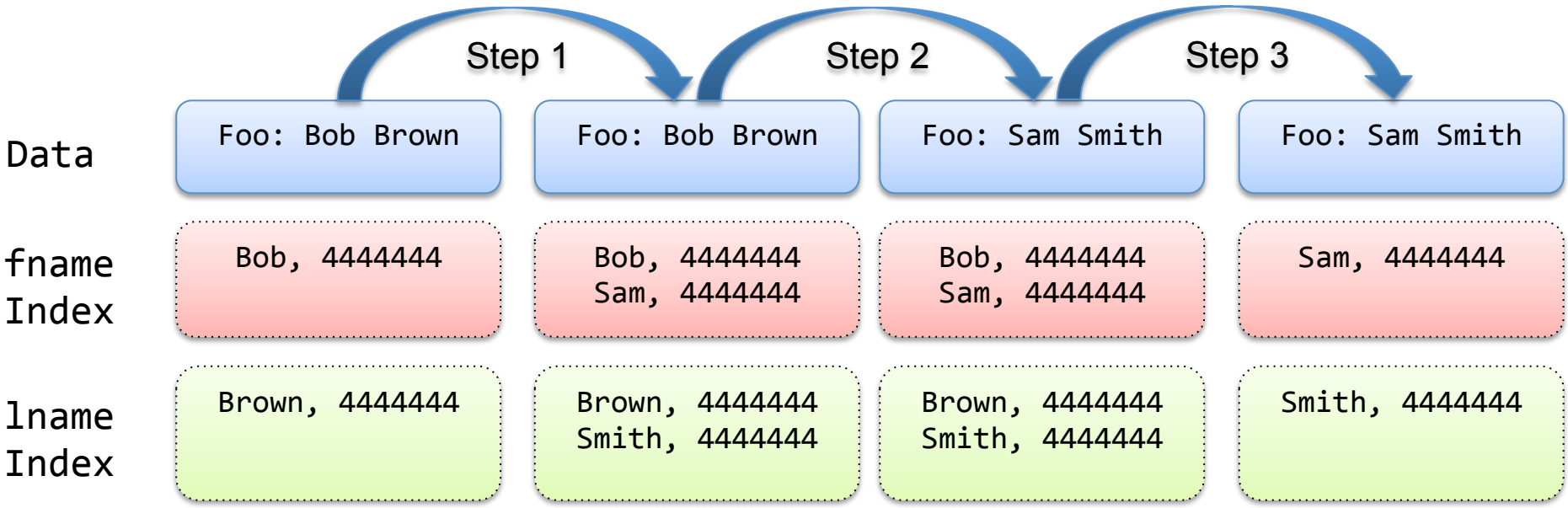

Summary

- **Secondary Indexes: lookups & range queries on attributes that are not the primary key**
- **Key design issues:**
  - Index partitioning
    - Co-locate with data
    - Partition based on index key
  - Failure / Restoration
    - Backup / recover
    - No backup / rebuild
  - Consistency: Linearizability
    - Key idea: Writing object is the commit point
- **Feedback welcome!**

Thank you!